

Sparse Bayesian Learning for Acoustic Source Localization

Acoustic source localization

Estimation of source position in realistic acoustic environment

Applications



- > To improve focusing on desired source
- Smart homes to interact with speaker
- Robots for awareness of occluded event
- > Smart cars for detecting vehicles
- > Intelligent monitoring system to recognize activity in their environment

Challenges



- > Reverberation
- > Interference and Noise
- > Dynamic targets
- Finding the number of sources

References



are defined by -

where d is the uniform inter-sensor spacing and θ_n is the nth DoA with respect to the array axis



Sparse Bayesian Learning (SBL)

- iterations.

[1] H. W. Löllmann et al. "The LOCATA challenge data corpus for acoustic source localization and tracking." SAM. IEEE, 2018. [2] R. Pandey, S. Nannuru and A. Siripuram, "Sparse Bayesian learning for acoustic source localization", ICASSP 2021 (Accepted)



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For a ULA with N sensors, the steering vectors $a(\theta_n) = e^{j2\pi \frac{d}{\lambda}[1 \ 2..N]sin(\theta_n)}$

Localization algorithms

Sparsity in DOA estimation

Consider the signal model to be:

$$\mathbf{y} = \mathbf{A}\mathbf{x} + \mathbf{n}$$
$$= \begin{bmatrix} a(\theta_1) \ a(\theta_2) \ \dots \ a(\theta_M) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ Y_{14} \end{bmatrix} + \begin{bmatrix} n_1 \\ n_2 \\ \vdots \\ \vdots \\ n_N \end{bmatrix}$$

where \mathbf{y} – received audio signal from microphones **A** – sensing matrix (steering vectors) **x** – source amplitude assume to be sparse **n** – additive noise in audio data

> SBL is a Compressive sensing method > Uses Bayesian framework to solve sparse problem > SBL formulates DOA estimation as a non-convex optimization problem and solves using fixed point

- and noisy environment

Multiple Signal Classification (MUSIC)

Results

- Dataset LOCATA dataset



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> It achieves high resolution and DOA estimates are reliable even with a single snapshot \succ It performs well even in the most complex **Conventional Beamforming (CBF)**

> CBF is the simplest method for source localization \succ It is robust to noise and have low resolution

> It is a high-resolution direction-finding algorithm > Capable of resolving closely-spaced signal sources \succ It needs multiple snapshots for better resolution

> Task : Localization of static and moving speaker